

### Citation Report

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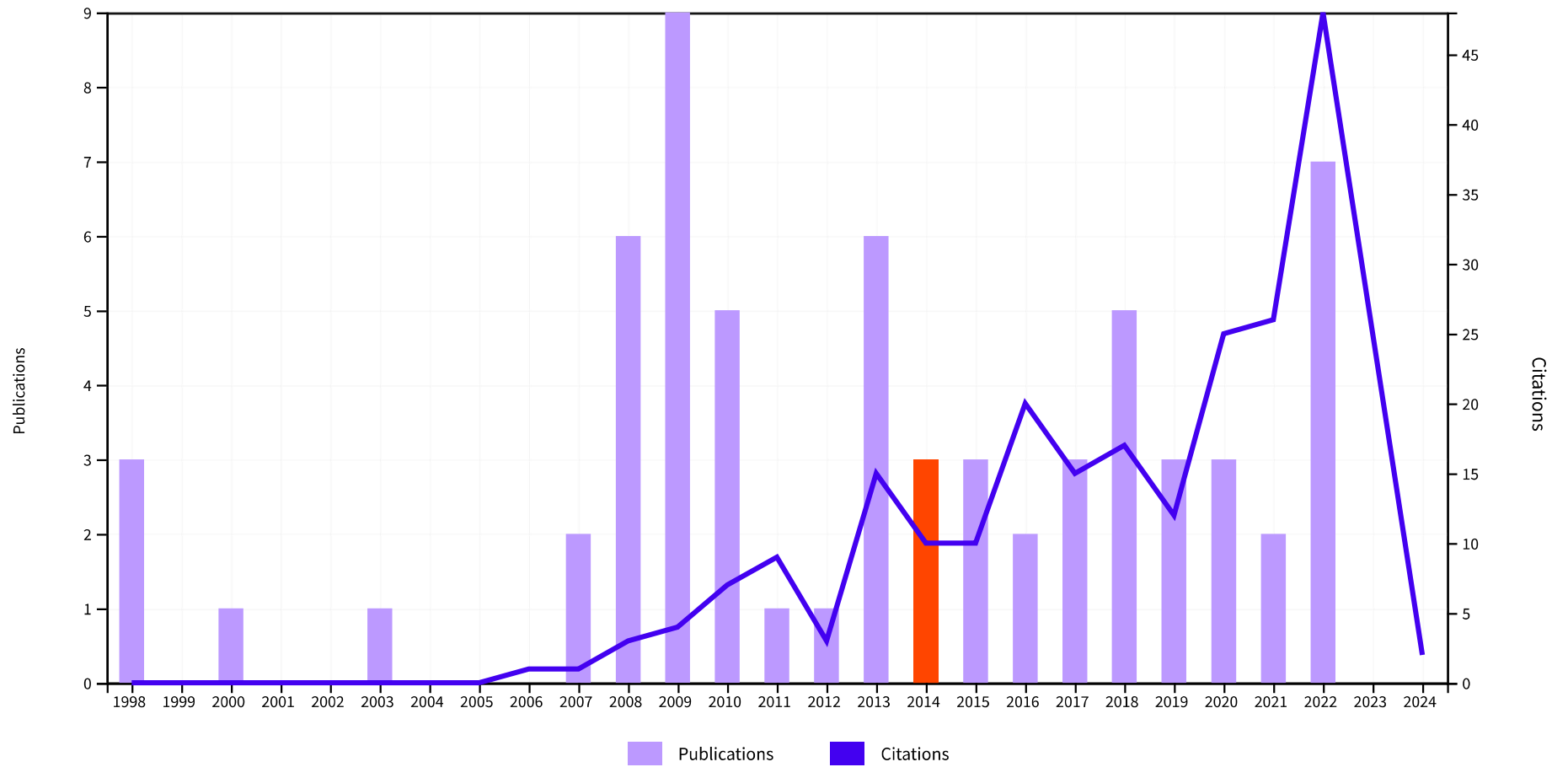
<p><b>Publications</b></p> <p><b>66</b> Total</p> <p>From 1975 ▾ to 2024 ▾</p>	<p><b>Citing Articles</b></p> <p><b>180</b> Analyze Total</p> <p><b>146</b> Analyze Without self-citations</p>	<p><b>Times Cited</b></p> <p><b>253</b> Total</p> <p><b>3.83</b> Average per item</p> <p><b>155</b> Without self-citations</p>	<p><b>8</b> H-Index</p>
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Citations: 10

Publications: 3

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### Times Cited and Publications Over Time







66 Publications

Sort by: Citations: highest first

< 2 of 2 >

#### Citations

< Previous year					Next year >		Average per year	Total 10
2020	2021	2022	2023	2024				

	Total	25	26	48	25	2	13.32	253
<p>51  <a href="#">Mechatronics Manufacturing Line with Integrated. Autonomous Robots and Visual Servoing Systems</a></p> <p><a href="#">Filipescu, A</a>; <a href="#">Minca, E</a> and <a href="#">Filipescu, A</a> 9th IEEE International Conference on Cybernetics and Intelligent Systems (CIS) / IEEE Conference on Robotics, Automation and Mechatronics (RAM) 2019   PROCEEDINGS OF THE IEEE 2019 9TH INTERNATIONAL CONFERENCE ON CYBERNETICS AND INTELLIGENT SYSTEMS (CIS) ROBOTICS, AUTOMATION AND MECHATRONICS (RAM) (CIS &amp; RAM 2019) , pp.422-427</p>		0	0	0	0	0	0	0
<p>52  <a href="#">Trajectory Tracking Nonlinear Control and Narrow Spaces Navigation of a WMR</a></p> <p><a href="#">Solea, R</a>; <a href="#">Ciubuciu, G</a>; (...); <a href="#">Voncila, J</a> 22nd International Conference on System Theory, Control and Computing (ICSTCC) 2018   2018 22ND INTERNATIONAL CONFERENCE ON SYSTEM THEORY, CONTROL AND COMPUTING (ICSTCC) , pp.329-334</p>		0	0	0	0	0	0	0
<p>53  <a href="#">SHPN Modelling, Visual Servoing and Control of WMR with RM Integrated into P/RML</a></p> <p><a href="#">Filipescu, A</a>; <a href="#">Solea, R</a>; (...); <a href="#">Petrea, G</a> 21st International Conference on System Theory, Control and Computing (ICSTCC) 2017   2017 21ST INTERNATIONAL CONFERENCE ON SYSTEM THEORY, CONTROL AND COMPUTING (ICSTCC) , pp.315-320</p>		0	0	0	0	0	0	0
<p>54  <a href="#">Sliding-Mode Control and Sonnar Based Bubble Rebound Obstacle Avoidance for a WMR</a></p> <p><a href="#">Filipescu, A</a>; <a href="#">Dumitrascu, B</a>; (...); <a href="#">Voda, A</a> 19th International Conference on System Theory, Control and Computing (ICSTCC) 2015   2015 19TH INTERNATIONAL CONFERENCE ON SYSTEM THEORY, CONTROL AND COMPUTING (ICSTCC) , pp.105-110</p>		0	0	0	0	0	0	0
<p><a href="#">Wheelchair Control and Navigation Based on Kinematic Model and Iris Movement</a></p>		0	0	0	0	0	0	10`

<p>⊖ 55</p> <p><a href="#">Solea, R; Filipescu, A; (...); Filipescu, S</a>          Proceedings of the 2015 7th IEEE International Conference on Cybernetics and Intelligent Systems (CIS) And Robotics, Automation and Mechatronics (RAM)          2015                     PROCEEDINGS OF THE 2015 7TH IEEE INTERNATIONAL CONFERENCE ON CYBERNETICS AND INTELLIGENT SYSTEMS (CIS) AND ROBOTICS, AUTOMATION AND MECHATRONICS (RAM)</p>								
<p>⊖ 56</p> <p><a href="#">Discrete-Time Sliding-Mode Control of Four Driving-Steering Wheels Autonomous Vehicle</a>  <a href="#">Dumitrascu, B; Filipescu, A; (...); Minca, E</a>          30th Chinese Control Conference          2011   2011 30TH CHINESE CONTROL CONFERENCE (CCC) , pp.3620-3625</p>		0	0	0	0	0	0	0
<p>⊖</p>		0	0	0	0	0	0	0
<p>⊖</p>		0	0	0	0	0	0	0
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